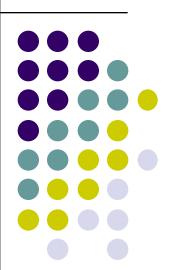
Module 6-1 Discrete Convolution Method

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Texas A&M University

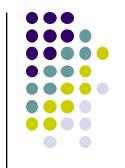


Basic Approach

- Generation System Model
- Load Model
- Generation Reserve Model

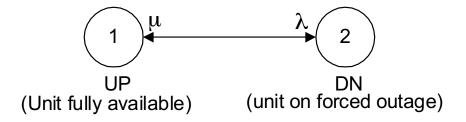
Other Features are Included by

- Modifying Generation System Model
 - Examples:
 - Energy Limited Units
 - Emergency Assistance
- Adjusting Load Model,
 - Examples:
 - Load Forecast Uncertainty
 - Interruptible Loads
 - Firm Interchanges

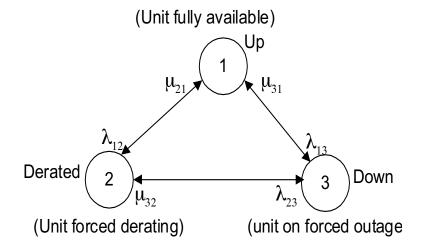


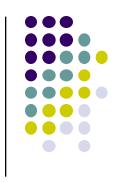
Generating Unit Model

Two State Unit Model

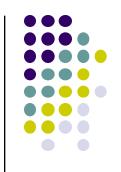


Three State Unit Model





Generating Unit Model



• If only probabilities are to be computed, then either λ and μ parameters can be used or DFORs (derated forced outage rates) and FORs (forced outage rates) of the units can be utilized.

Then for,

Two-State Unit

$$p2 = FOR$$

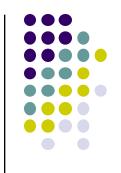
Three-State Unit

$$p2 = DFOR$$

and

$$p3 = FOR$$





 Another approach which has been used in the past, and is still used by many utilities, is to model forced deratings as equivalent full forced outages. In this approach, all units can be represented by two-state models with

$$p2 = DAFOR$$

where

DAFOR = equivalent FOR



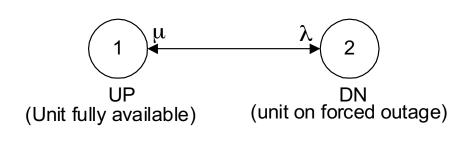


- P_i = probability of the unit state i
- f_{ij} = frequency of transition from unit state i to j
- Two-State Unit

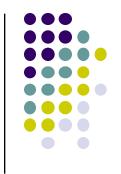
$$\mathbf{p_1} = \frac{\mu}{\lambda + \mu}$$

$$\mathbf{p_2} = \frac{\lambda}{\lambda + \mu}$$

$$\mathbf{f_{12}} = \mathbf{f_{21}} = \frac{\lambda \mu}{\lambda + \mu}$$







Three-State Unit

$$\mathbf{P_1} = \frac{Q_1}{Q_1 + Q_2 + Q_3}$$

$$\mathbf{P_2} = \frac{Q_2}{Q_1 + Q_2 + Q_3}$$

$$\mathbf{P_3} = \frac{Q_3}{Q_1 + Q_2 + Q_3}$$

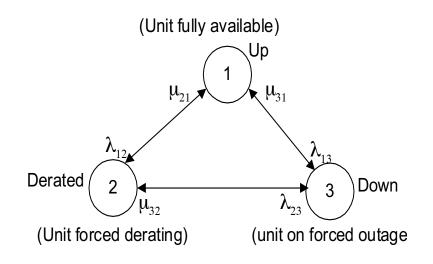
where

$$Q_1 = \mu_{21}\,\mu_{32} + \mu_{31}\,\mu_{21} + \mu_{31}\,\lambda_{23}$$

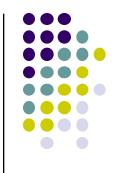
$$\mathbf{Q}_2 = \ \mu_{32} \, \lambda_{12} + \mu_{32} \, \lambda_{13} + \lambda_{12} \, \mu_{31}$$

and

$$Q_3 = \lambda_{12} \lambda_{23} + \lambda_{13} \mu_{21} + \lambda_{13} \lambda_{23}$$



Modeling Immature Units



•
$$V(t) = Vi - m * t$$

where

V(t) = parameter value at time t

Vi = initial value of the parameter

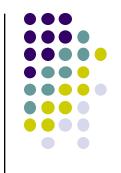
m = (Vi - Vf)/D

Vf = mature value of the parameter

and

D = duration of immaturity





Described by three vectors C, P and F:

Ci = ith element of C

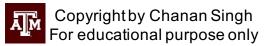
= one of the discrete capacity outage levels

Pi = ith element of P

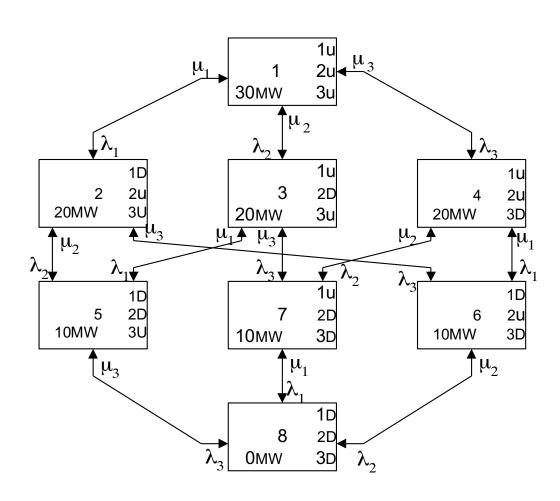
= probability of capacity outage greater than or equal to Ci

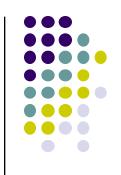
Fi = ith element of F

= frequency of capacity outage greater than or equal to Ci









Capacity	Capacity Out	Exact State Prob.	Cum. Prob. P(Cap out ≥ X)
30	0	$P'_1 = P (Capout = 0)$	$P_1 = P_2 + P'_1$
20	10	P' ₂ = P (Capout = 10)	$P_2 = P_3 + P'_2$
10	20	$P'_3 = P (Capout = 20)$	$P_3 = P_4 + P'_3$
0	30	P' ₄ = P (Capout = 30)	$P_4 = P'_4$



Exact State Frequency

F (Capout = 20) =
$$p_5 (\mu_1 + \mu_2 + \lambda_3) + p_7 (\mu_2 + \mu_3 + \lambda_1) + p_6 (\mu_1 + \mu_3 + \lambda_2)$$

$$F(Capout \ge 20) \ne F(Capout = 20) + F(Capout = 30)$$





Assume that a capacity outage table exists:

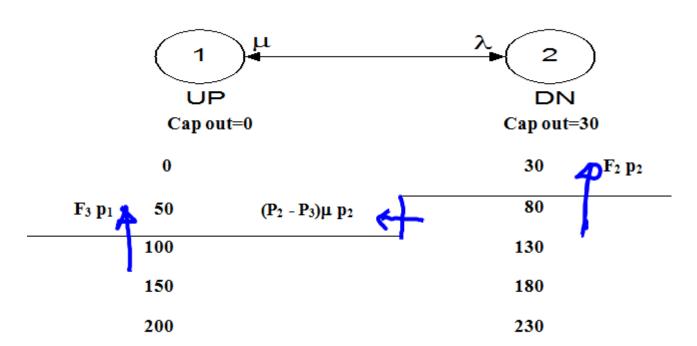
i	C_i	$\mathbf{P_i}$	$\mathbf{F_{i}}$
1	0	$\mathbf{P}_{\mathbf{l}}$	$\mathbf{F_1}$
2	50	\mathbf{P}_2	$\mathbf{F_2}$
3	100	\mathbf{P}_3	\mathbf{F}_3
4	150	\mathbf{P}_4	\mathbf{F}_4
5	200	P_5	\mathbf{F}_{5}

Add a 2- State Unit of 30 MW

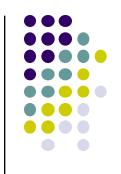




Add a 2- State Unit of 30 MW



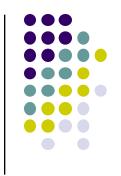




i	$\mathbf{C_{i}}$	$\mathbf{P_{i}}$	$\mathbf{F_{i}}$	1 <u> </u>	λ 2
				UP	DN
1	0	$\mathbf{P_1}$	$\mathbf{F_1}$	Cap out=0	Cap out=30
2	50	$\mathbf{P_2}$	$\mathbf{F_2}$	0	30 P F ₂ p ₂
3	100	\mathbf{P}_3	\mathbf{F}_3	$F_3 p_1$ 50 $(P_2 - P_3)\mu p_2$	80
4	150	\mathbf{P}_4	$\mathbf{F_4}$	100 150	130 180
5	200	P_5	$\mathbf{F_5}$	200	230

$$\begin{array}{ll} P \ (C \geq 80) &= Probability \ of \ capacity \ outage \ greater \ than \ or \ equal \ to \\ 80MW \\ &= P_2 \ p_2 + P_3 \ p_1 \\ F \ (C \geq 80) &= Frequency \ of \ capacity \ outage \geq 80MW \\ &= F_2 \ p_2 + F_3 \ p_1 + (P_2 - P_3) \ \mu \ p_2 \end{array}$$





- The algorithm described in this section is used for embedding a unit model in the generation system model.
- Assume that the capacity outage states are arranged in ascending order of magnitude. Let x_i be the capacity outage in state i. The addition of a 3-state unit, results in three subsets of states (refer to Fig 1.).

```
S_1 = \{x_i\}

S_2 = \{x_i + C_D\}

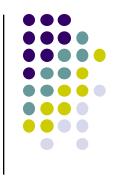
S_3 = \{x_i + C_T\}
```

where

 C_T = capacity of unit being added.

 C_D = amount of capacity lost when unit being added is derated.

Unit Addition Algorithm



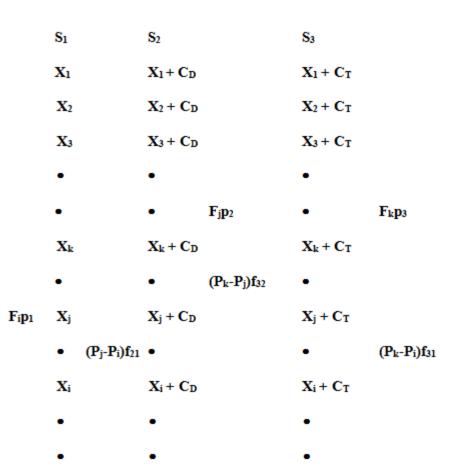
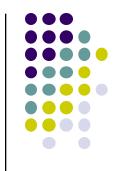


Fig. 1 State Frequency Diagram for Unit Addition





 These three subsets, arranged as three columns in Fig. 1, have an equal number of states and in each the capacity outages are arranged in an ascending order. Assuming that a capacity equal to or greater than X is defined by states equal to and greater than i, j and k in S1, S2 and S3 respectively,

$$P(X) = P_i \ p_1 + P_j \ p_2 + P_k \ p_3 \qquad \text{where}$$

$$G(X) = F_i \ p_1 + F_j \ p_2 + F_k \ p_3$$

$$F(X) = G(X) + N(X) \qquad N(X) = (P_j - P_i) \ f_{21} + (P_k - P_i) \ f_{31} + (P_k - P_j) \ f_{32}$$
 and
$$P_i, \ F_i \qquad = probability \ and \ frequency \ of \ capacity \ outage \ equal \ to \ or \ greater \ than \ x_i.$$

 It should be noted that G(X) represents the frequency due to change in the states of the units other than the unit being added.



Capacity	Exact State Prob.	Cum. Prob. P(Cap out ≥ X)
30	$P'_1 = P (Cap = 30)$	$P_1 = P_2 + P'_1$
20	$P'_2 = P (Cap = 20)$	$P_2 = P_3 + P'_2$
10	$P'_3 = P (Cap = 10)$	$P_3 = P_4 + P'_3$
0	$P'_4 = P (Cap = 0)$	$P_4 = P'_4$

Exact State Frequency

$$F(Cap = 10) = p_5(\mu_1 + \mu_2 + \lambda_3) + p_7(\mu_2 + \mu_3 + \lambda_1) + p_6(\mu_1 + \mu_3 + \lambda_2)$$

$$F(Cap \le 10) \ne F(Cap = 10) + F(Cap = 0)$$