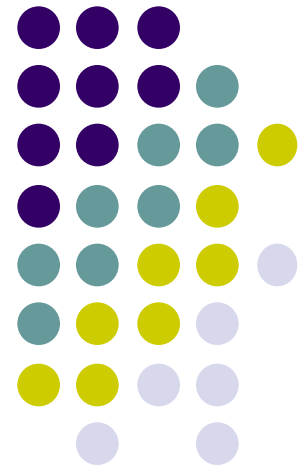
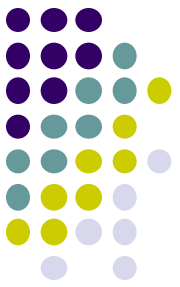


Module 2-2

Review of Probability Theory

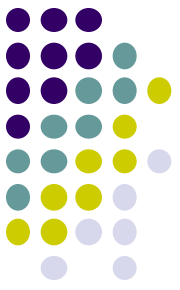
Chanan Singh
Texas A&M University





Outline

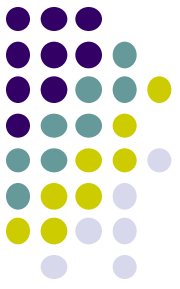
- Random variable
 - Probability distribution function
 - Survival function
 - Hazard function
 - Exponential distribution function
- Stochastic processes
- Markov process
 - Transition probability
 - Transition rate matrix



Random Variable (RV)

A function that assigns numerical values to all possible outcomes of a state space

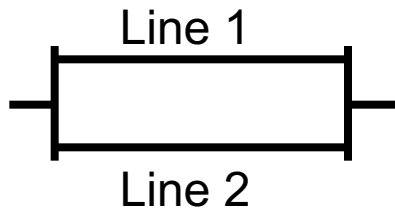
- Discrete RV assigns discrete value.
 - Ex: A number of components down in power system
- Continuous RV assigns continuous value.
 - Ex: Time to failure of a component



Discrete RV: Number of T-Lines Down

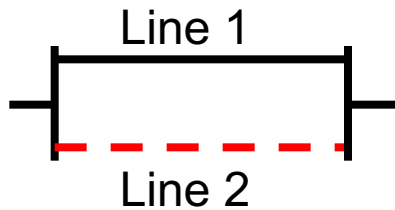
Outcomes

Random Variable



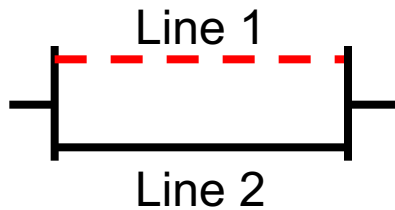
(1 Up, 2 Up)

0

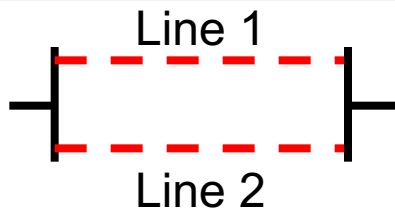


(1 Up, 2 Down)

1



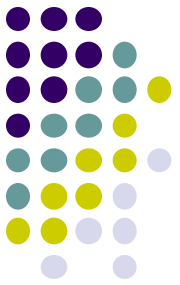
(1 Down, 2 Up)



(1 Down, 2 Down)

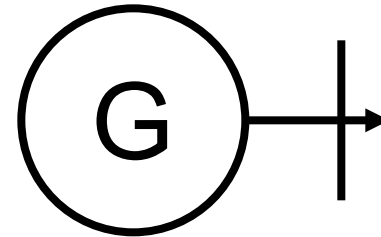
2





Continuous RV: Time to Failure

A generator start working at time $x = 0$



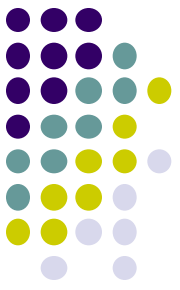
Outcomes: time to failure

It can fail at any time, $x \geq 0$

Random Variable, X

$$x \geq 0$$



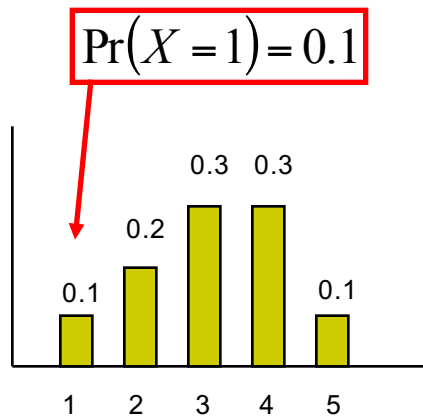


Probability Distribution Function

A function that gives probabilities associated with all possible values of a random variable.

$$f_X(x) = \lim_{\Delta x \rightarrow 0} \frac{\Pr(x < X < x + \Delta x)}{\Delta x}$$

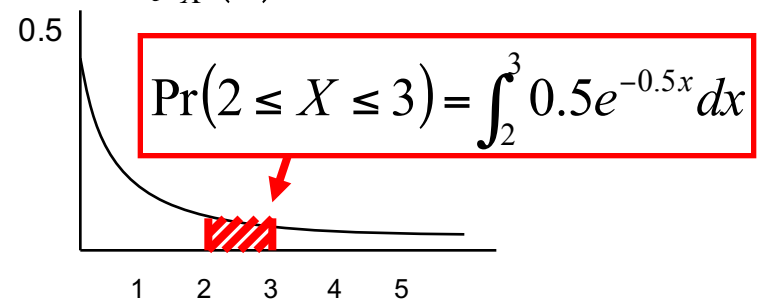
- Discrete RV:

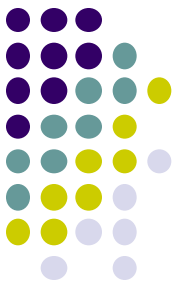


- Continuous RV:

Exponential distribution function

$$f_X(x) = 0.5e^{-0.5x}, x \geq 0$$





Discrete Random Variable

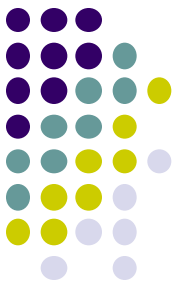
- Probability density or mass function

Properties

$p_X(x) = 0$ unless x is one of the values of the discrete rv, x_1, x_2, \dots

$$0 \leq p_X(x_i) \leq 1$$

$$\sum_i p_X(x) = \sum_i P(X = x_i) = 1$$



Continuous Random Variable

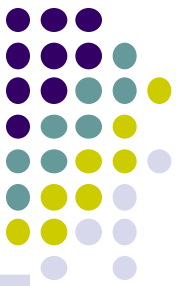
$$P[a \leq X \leq b] = \int_a^b f_X(y) dy$$

Properties

i $f_X(x)$ is non-negative

ii
$$\int_{-\infty}^{+\infty} f(x) dx = 1$$

iii The function $f(x)$ is continuous at all but finite number of points, ie, it is piece-wise continuous

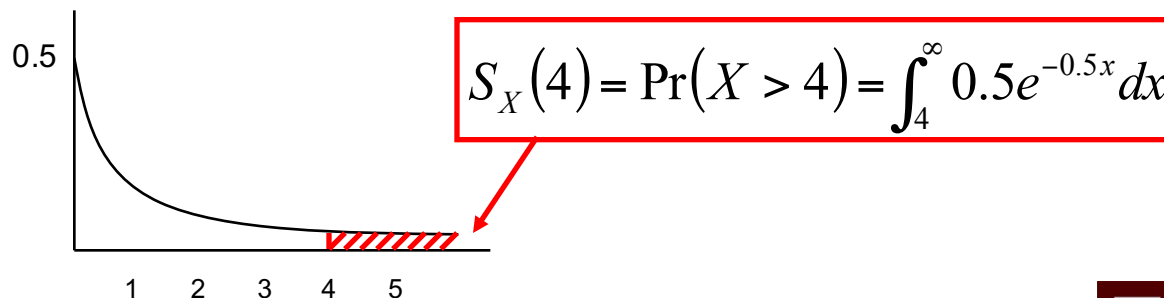


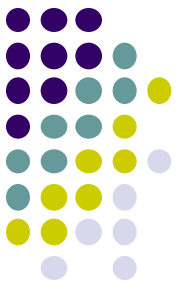
Survival Function

A function that gives probability of a component survival beyond time x .

$$S_X(x) = \Pr(X > x)$$

- Time to failure of a component is a random variable.
- This rv is commonly used in reliability theory



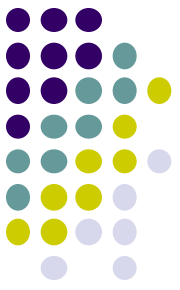


Distribution Function

A function that gives probability of a component failing by time x .

$$F_X(x) = \Pr(X \leq x)$$

$$F_X(x) = 1 - S_X(x)$$



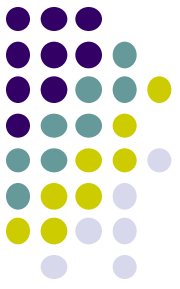
Hazard Function

A function that gives a rate at time x , at which a component fails (i.e. failure rate), given that it has survived for time x .

- Denoted by $\phi(x)$,

Probability of a component fails between time x and $x+\Delta x$ given that it has survived for time x

$$\phi_X(x) = \lim_{\Delta x \rightarrow 0} \frac{\Pr(x < X < x + \Delta x \mid X > x)}{\Delta x}$$



Hazard Function

- From,

$$\phi_X(x) = \lim_{\Delta x \rightarrow 0} \frac{\Pr(x < X < x + \Delta x \mid X > x)}{\Delta x}$$

- We have

$$\phi_X(x) = \lim_{\Delta x \rightarrow 0} \frac{\Pr(x < X < x + \Delta x)}{\Delta x} \cdot \frac{1}{\Pr(X > x)}$$

$$\phi_X(x) = \frac{f_X(x)}{S_X(x)}$$

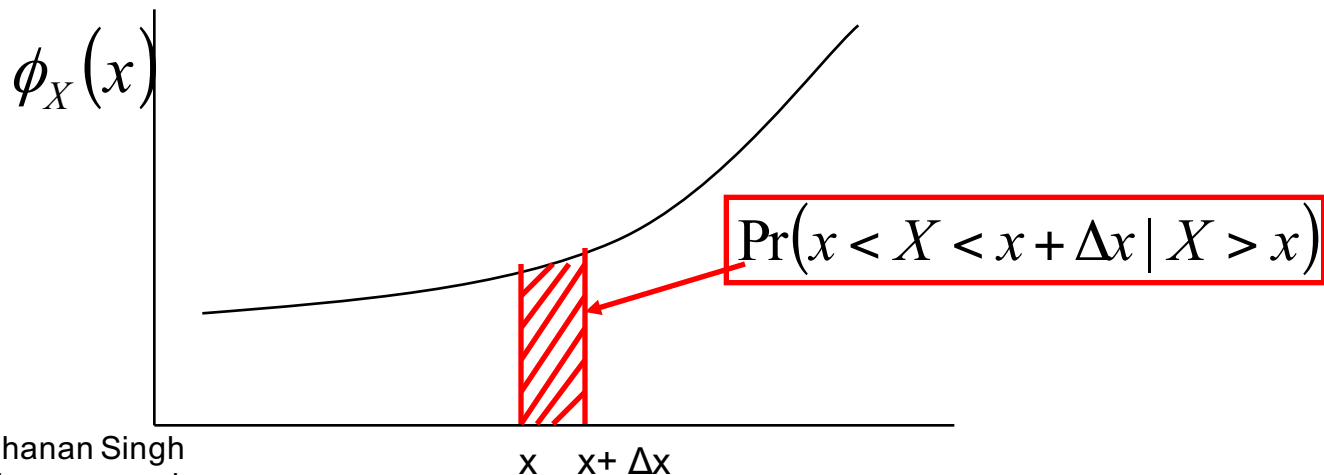


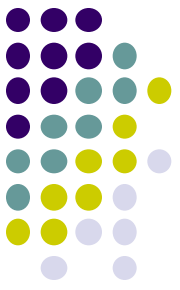
An Important Relationship

- From hazard function as $\Delta x \rightarrow 0$,

$$\phi_X(x)\Delta x = \Pr(x < X < x + \Delta x \mid X > x)$$

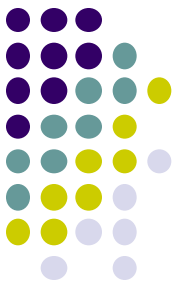
- This gives probability of failure of a component in interval $(x, x + \Delta x)$.





Important Note

- Although , for simplicity, survival function and hazard rate function have been described with respect to a component failure, they apply to any random variable.
- For example if the random variable is time to repair, then $\Phi(x)$ represents the repair rate



Expected Value

For discrete random variable

$$\begin{aligned} E(X) &= \sum_i x_i P(X = x_i) \\ &= \sum_i x_i p(x_i) \end{aligned}$$

For continuous random variable

$$E(X) = \int_{-\infty}^{\infty} x f(x) dx$$



Mean and Average

Consider a random sample of n observations of X . Then the sample mean

$$\bar{X} = \frac{X_1 + X_2 + \cdots + X_n}{n}$$

According to the law of large numbers, for any constant $c > 0$

$$\lim_{n \rightarrow \infty} P[|\bar{X} - m| > c] = 0$$

Where m is the mean of x

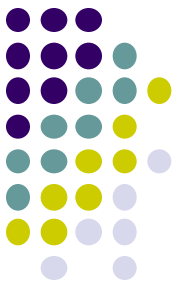
Thus as sample size increases, the sample mean approaches the mean value of rv .



Sum of Random Variables

$$E\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n E(X_i)$$

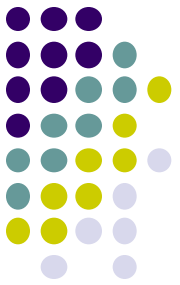
This result holds even when the random variables are not independent.



Variance

$$\begin{aligned} V(X) &= E \left[(X - E(X))^2 \right] \\ &= \sum_i (x_i - m)^2 p_i(x) \quad \text{for discrete rv} \\ &= \int_{-\infty}^{\infty} (x - m)^2 f(x) dx \quad \text{for continuous rv} \end{aligned}$$

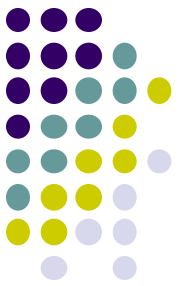
Variance provides a measure of spread of the distribution



Variance

$$\begin{aligned}V(X) &= E \left[(X - E(X))^2 \right] \\&= E \left[X^2 + (E(X))^2 - 2XE(X) \right] \\&= E(X^2) - (E(X))^2\end{aligned}$$

This relationship is easier to implement



Covariance

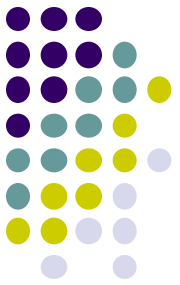
A measure of the tendency of two random variables to vary together.

$$\begin{aligned} \text{Cov}(X, Y) &= E[(X - E(X))(Y - E(Y))] \\ &= E(XY) - E(X)E(Y) \end{aligned}$$

Correlation Coefficient

$$C_{XY} = \frac{\text{Cov}(X, Y)}{\sqrt{V(X)V(Y)}}$$

Range (-1, 1)



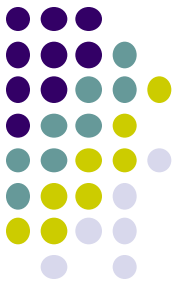
Covariance

If X, Y are independent

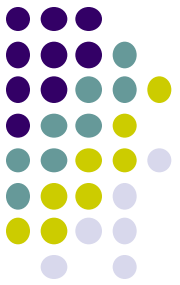
$$C_{XY} = 0$$

But reverse is not always true

Expectation of a Real Valued Function $g(X)$



$$E[g(X)] = \sum_i g(x_i) p(x_i) \quad \text{for drv}$$
$$= \int_{-\infty}^{\infty} g(x) f(x) dx \quad \text{for crv}$$



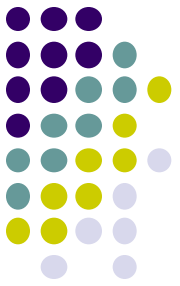
Moments

Let $g(X) = X^k$

Then the k th initial moment of X

$$\begin{aligned} m_k(X) &= m_k \\ &= \sum x_i^k p(x_i) && \text{for drv} \\ &= \int_{-\infty}^{\infty} x^k f(x) dx && \text{for crv} \end{aligned}$$

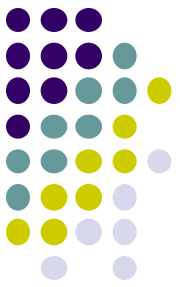
Moments around Mean or Central Moments



$$\begin{aligned}M_k(X) &= M_k \\&= \sum_{i=1}^n (x_i - m)^k p(x_i) && \text{for drv} \\&= \int_{-\infty}^{\infty} (x - m)^k f(x) dx && \text{for crv}\end{aligned}$$

Transform Methods

Characteristic Function of X



$$\begin{aligned}\phi_X(\theta) &= E[e^{i\theta X}] \\ &= \int_{-\infty}^{\infty} e^{i\theta x} f(x) dx\end{aligned}$$

where $i = \sqrt{-1}$

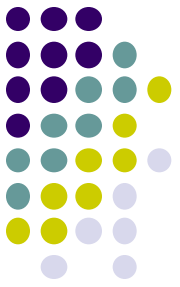
$f(x)$ = pdf of x

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \phi(\theta) e^{-i\theta x} d\theta$$

One to one correspondence between pdf & CF

CF and Moments

Differentiate CF k times



$$\phi^{(k)}(\theta) = \frac{d^k \phi(\theta)}{d\theta^k} = i^k \int_{-\infty}^{\infty} x^k e^{i\theta x} f(x) dx$$

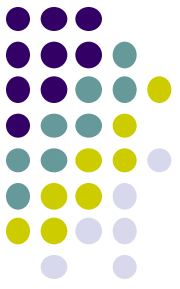
As $\theta \rightarrow 0$

$$\begin{aligned}\phi^{(k)}(0) &= i^k \int_{-\infty}^{\infty} x^k f(x) dx \\ &= i^k m_k\end{aligned}$$

or

$$m_k = i^{-k} \phi^{(k)}(0)$$

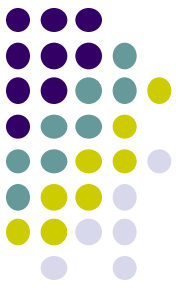
CF of Sum of Random Variables



$$Y = X_1 + X_2 + \cdots + X_n$$

Where X_i are independent

$$\begin{aligned}\phi_Y(\theta) &= E(e^{i\theta Y}) \\ &= E(e^{i\theta(X_1+X_2+\cdots+X_n)}) \\ &= E(e^{i\theta X_1})E(e^{i\theta X_2}) \dots E(e^{i\theta X_n}) \\ &= \phi_{X_1}(\theta)\phi_{X_2}(\theta)\dots\phi_{X_n}(\theta)\end{aligned}$$



Moment Generating Function

For real numbers

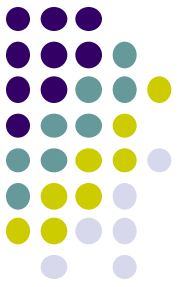
$$\begin{aligned}\psi(\theta) &= E(e^{\theta X}) \\ &= \int_{-\infty}^{\infty} e^{\theta x} f(x) dx && \text{for crv} \\ &= \sum_i e^{\theta x_i} p(x_i) && \text{for drv}\end{aligned}$$

Here

$$m_k = \psi^{(k)}(0)$$

Moment Generating Function

About mean m (or any point)



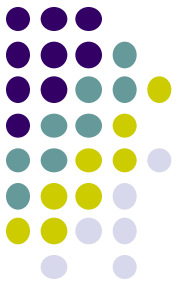
$$\begin{aligned}\Psi_m(\theta) &= E(e^{(X-m)\theta}) \\ &= e^{-m\theta}\Psi(\theta)\end{aligned}$$

The k th moment about mean

$$M_k = \Psi_m^{(k)}(0)$$

Laplace transform

(If X is non-negative)



$$L(g(t)) = \bar{g}(s) = \int_0^{\infty} g(t)e^{-st} dt$$

Compare with moment generating function

$$\theta = -s$$

$$\begin{aligned}\bar{f}(s) &= E(e^{-sX}) \\ &= E\left[\sum_{k=0}^{\infty} (-1)^k \frac{s^k X^k}{k!}\right] \\ &= \sum_{k=0}^{\infty} (-1)^k \frac{s^k}{k!} m_k\end{aligned}$$

Some Special Distributions

Exponential Distribution



A non-negative rv is said to have negative exponential distribution if probability density function is

$$f(x) = \rho e^{-\rho x}$$

ρ is a positive constant

$$F(x) = \int_0^x \rho e^{-\rho u} du = 1 - e^{-\rho x}$$

$$S(x) = 1 - F(x) = e^{-\rho x}$$

Some Special Distributions

Exponential Distribution



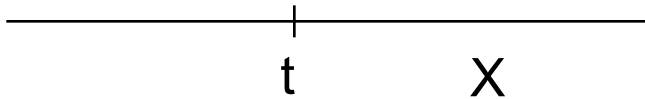
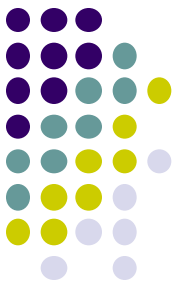
$$\phi(x) = \frac{f(x)}{S(x)} = \rho$$

$$\text{Mean} = \frac{1}{\rho}$$

$$\text{Variance} = \frac{1}{\rho^2}$$

$$\text{Standard dev} = \sqrt{\text{Variance}} = \frac{1}{\rho}$$

Distribution of Residual Life Time



$$Y = X - t$$

$$F_Y(x) = P[(X - t) \leq x \mid X > t]$$

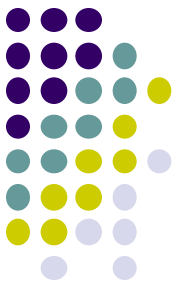
$$= P[X \leq x + t \mid X > t]$$

$$= P[t < X \leq x + t] / P[X > t]$$

$$= \frac{\int_t^{x+t} \rho e^{-\rho u} du}{e^{-\rho t}}$$

$$= 1 - e^{-\rho x}$$

$$= F_X(x)$$



Poisson Distribution

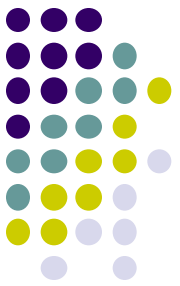
If the number of events is given by Poisson distribution, in time t

$$\begin{aligned} p_k(t) &= P(\text{No of events} = k) \\ &= \frac{(\lambda t)^k e^{-\lambda t}}{k!} \end{aligned}$$

So probability of no failures during $(0,t)$

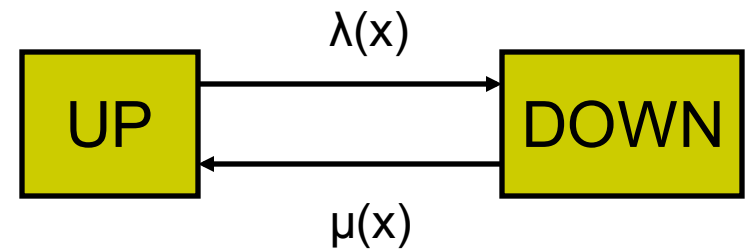
$$1 - F(t) = e^{-\lambda t}$$

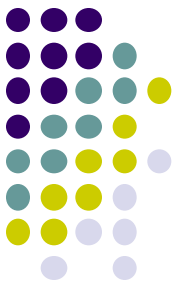
This is exponential distribution



A Two-State Component

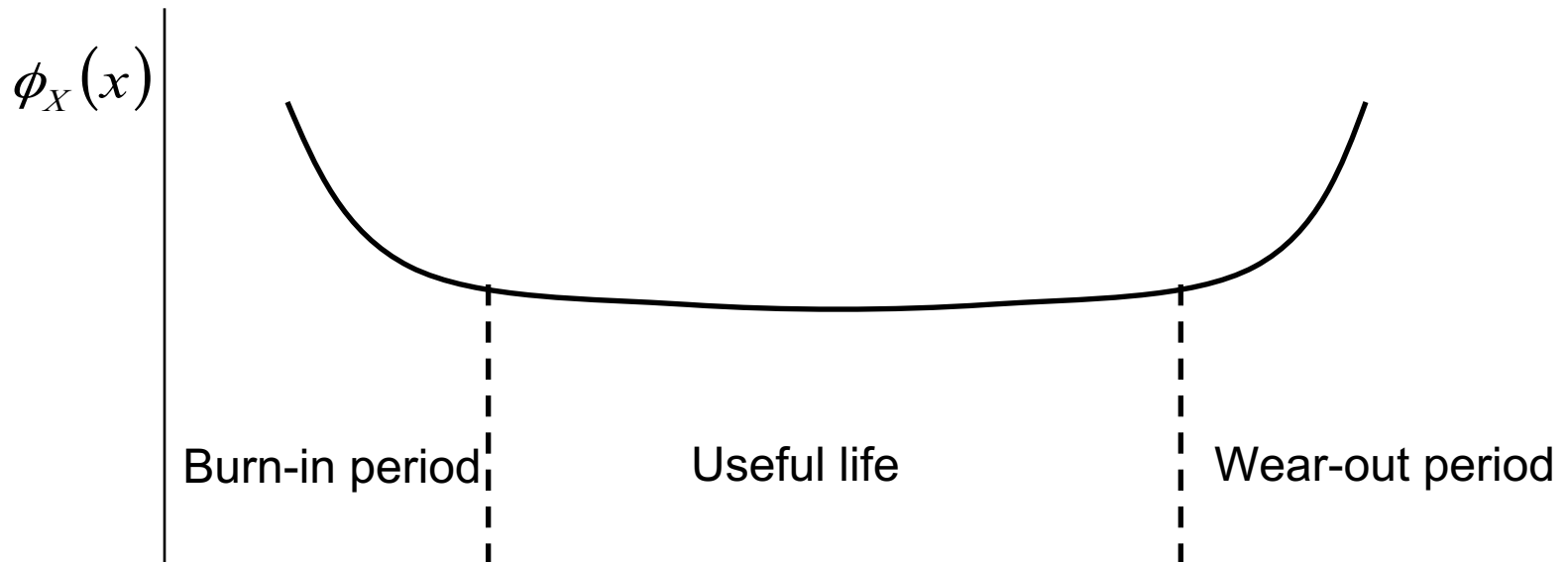
- Consider a two-state component
- $\lambda(x)$ is a hazard function of the up time, called failure rate.
- $\mu(x)$ is a hazard function of the down time, called repair rate.
- Generally, hazard function is called '*transition rate*' in reliability work.



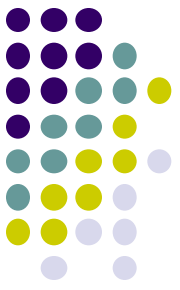


A Bath Tub Curve

- Typical hazard function of a component.



- It is fairly common to assume constant transition rates in reliability modeling.



Exponential Distribution Function

- Non-negative continuous random variable
- Commonly used to represent up time of a component

$$f_X(x) = \lambda e^{-\lambda x}, x \geq 0$$

$$S_X(x) = e^{-\lambda x}, x \geq 0$$

$$\phi_X(x) = \lambda, x \geq 0$$

- If we assume up time and repair time of a component are exponentially distributed, the failure rate and repair rate are *constant*.